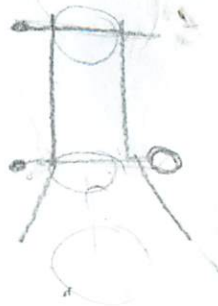
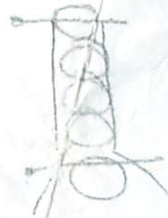
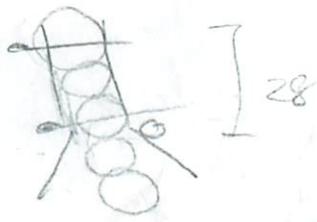
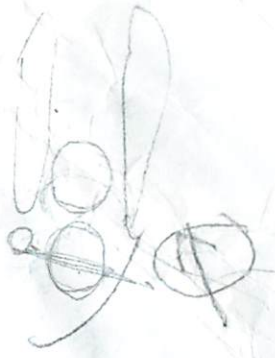


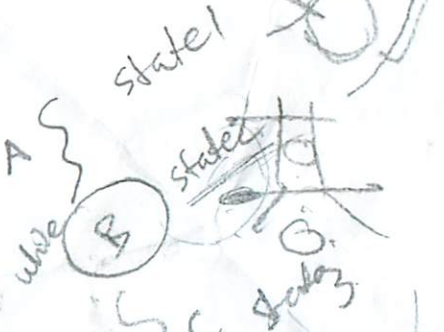
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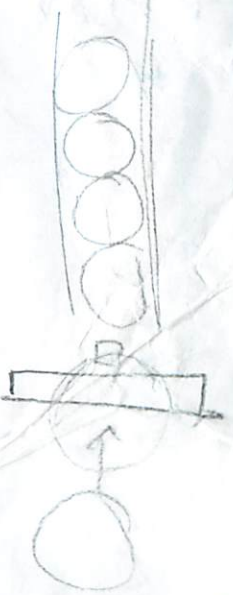
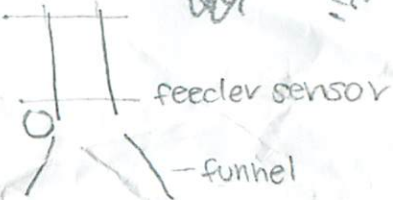
funnel & feeder (Speed) until sensor feeder



L-sensor	U-sensor	lower action	rot action
1	0	stop	stop
1	1	run	run
0	1	stop	stop
0	0	run	run



run elevator until !L
elevator feeder until !U
loop until T



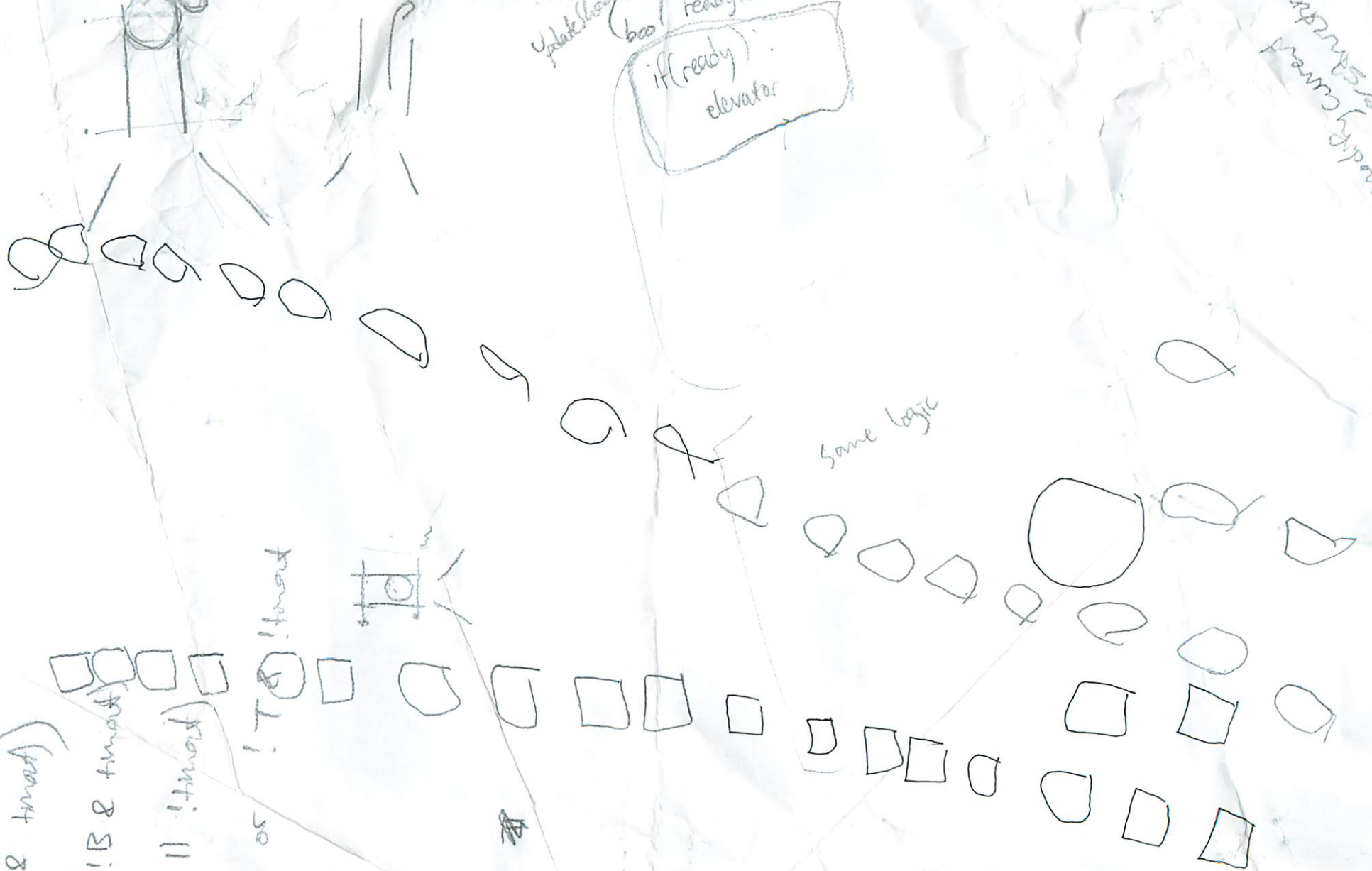
if (funnel A + Speed() < desired speed in range) (Needs testing, see feedback)

ready current
ready current

if (ready) elevator

up/down
bea

same logic



Alison Soong